SID 2008





Transitions of Step Responses



Luminance versus time: two well conditioned monotonous transitions between two optical states, S₁, S₂,without artefacts, e.g. fluctuations, modulations, overshoot or undershoot.

Transitions characterized by response-time period ($t_{90} - t_{10}$)

Modulations



Filtering



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Optical Transient Recorder



Recording of optical transients:

bandwidth control,

avoid ringing, clipping, latch-up,

- oversampling (10k samples per set),
- matched timing of DUT driving + luminance sampling,
- numerical data processing (filtering) in computer.



Moving Window Averaging

Moving Window Averaging (Convolution):

- effective,
- precisely matched to target frequency (e.g. modulation),
- easy to implement.



Moving Window Averaging



luminance = f(t)

$$f(t) \otimes \operatorname{Rect}(T_m) = F(\omega) \cdot \frac{\sin \omega}{\omega}$$

 $\omega = 2\pi / T_m$

convolution of f(t) with rectangular window Rect(T_m) = multiplication of Fourier spectrum of f(t) = F(ω) with sinc(ω):

 $f(t) \otimes \text{Rect}(T_m) = F(\omega) \cdot \text{sinc}(\omega)$

 \Rightarrow removal of all harmonics of 1/T_m



Model Functions for Transitions



Model Functions for Transitions



Modification of Transitions



Modification of Transitions



Correction Factor from Logistic Function



Example



104 Hz backlight modulation, transition period $(t_{90}-t_{10})^*$ of 9.7 ms,

 $T_{MA}/(t_{90}-t_{10})^* = 0.9897 \rightarrow corr. factor ~0.63$ (i.e. 6.1ms instead of 9.7ms).

Overdriven Overdrive



Transition model functions are monotonous

Overdriven Overdrive



Transition model functions are monotonous

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Transition $\tau(t)$ obscured by backlight modulation, b(t) and noise, v(t).

$$\tau(t) = \frac{y(t)}{b(t) + v(t)}$$

The backlight modulation function b(t) can be obtained

- from plateaus (t $\rightarrow \infty$) where τ (t) has settled,
- from separate measurements of the constant state.

Details of this approach, e.g. how to determine the correct **phase** of the function b(t) will be described in a forthcoming publication by Tobias Elze.

Extended Approach Applied



Overdrive Adjusted



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Limitations

 For infinitely fast transitions (e.g. step functions) and when b(t) adds a steep gradient to the transition τ(t),

 $\begin{array}{l} (t_{90} - t_{10})^* \to 0.8 \!\cdot\! T_{MA} \text{ and thus} \\ T_{MA} / \, (t_{90} - t_{10})^* \to 1.25, \end{array}$

depending on the phase of b(t).

- For values close to 1.25 it becomes increasingly difficult to accurately determine the correction factor because of the steepness of the curve.
- Overshoot not (yet) considered by model functions.

Benefits

LCD response time evaluation in the presence of luminance modulations.

- The method is simple and easy to implement,
- it considerably improves the accuracy of evaluation of transition times in typical practical cases and thus the data specifying LCD-dynamics.
- A second method that overcomes the limitations of the first approach has been outlined additionally.
- Both methods together are a solid basis for realistic evaluation and specification of the dynamics of LCDs.

Thank you very much for your attention



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